

OPERATION MANUAL

DIGIFORCE[®] 9307 PROFINET Integration into TIA Portal

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Applies to: **DIGIFORCE[®] 9307-V0X03**

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Introduction

This quick start guide describes an approach how you can configure the DIGIFORCE[®] 9307 via TIA Portal using the example of S7-1511 CPU. Please note that the samples here cannot be directly used in your production line because they have been extremely simplified to reach a better understanding. Therefore, you may have to complete them by checking of status, error, length values etc.

Please also note that you will have to use the DIGIFORCE[®] 9307 PROFINET manual to get further information about input and output parameters (cyclic as well acyclic data transfer)

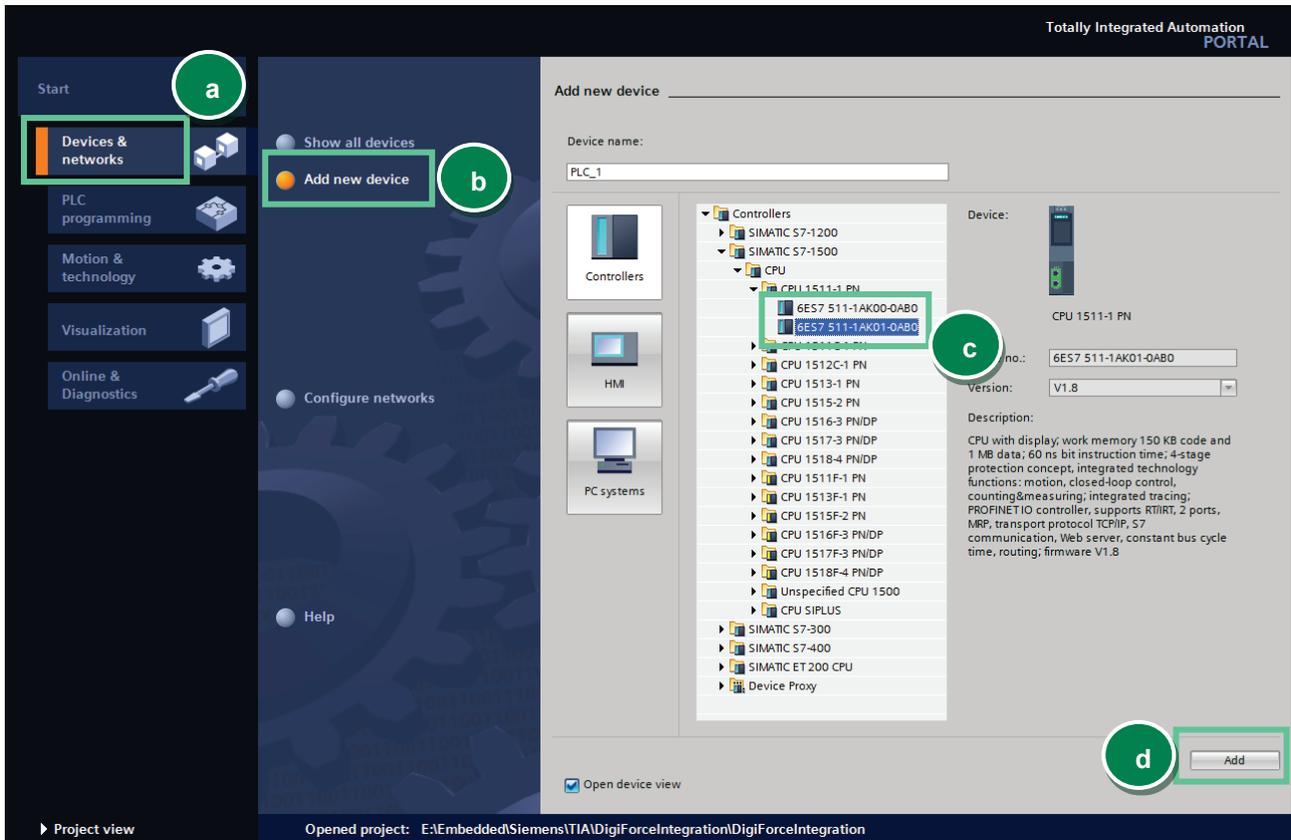
1. Creating new project

- Start the **Totally Integrated Automation Portal**, select **Create New Project** (a), assign the project a name (b) and click **Create** (c):

The screenshot displays the 'Totally Integrated Automation PORTAL' interface. On the left, a navigation menu includes 'Start', 'Devices & networks', 'PLC programming', 'Motion & technology', 'Visualization', and 'Online & Diagnostics'. The main area shows a list of actions: 'Open existing project', 'Create new project' (highlighted with a green box and labeled 'a'), 'Migrate project', 'Close project', 'Welcome Tour', 'First steps', 'Installed software', 'Help', and 'User interface language'. On the right, the 'Create new project' form is visible, with the 'Project name' field containing 'DigiForceIntegration' (labeled 'b') and the 'Create' button (labeled 'c'). The status bar at the bottom indicates 'Opened project: E:\Embedded\Siemens\TIA\...\DigiForce 9307 GettingStarted'.

DIGIFORCE[®] 9307 PROFINET

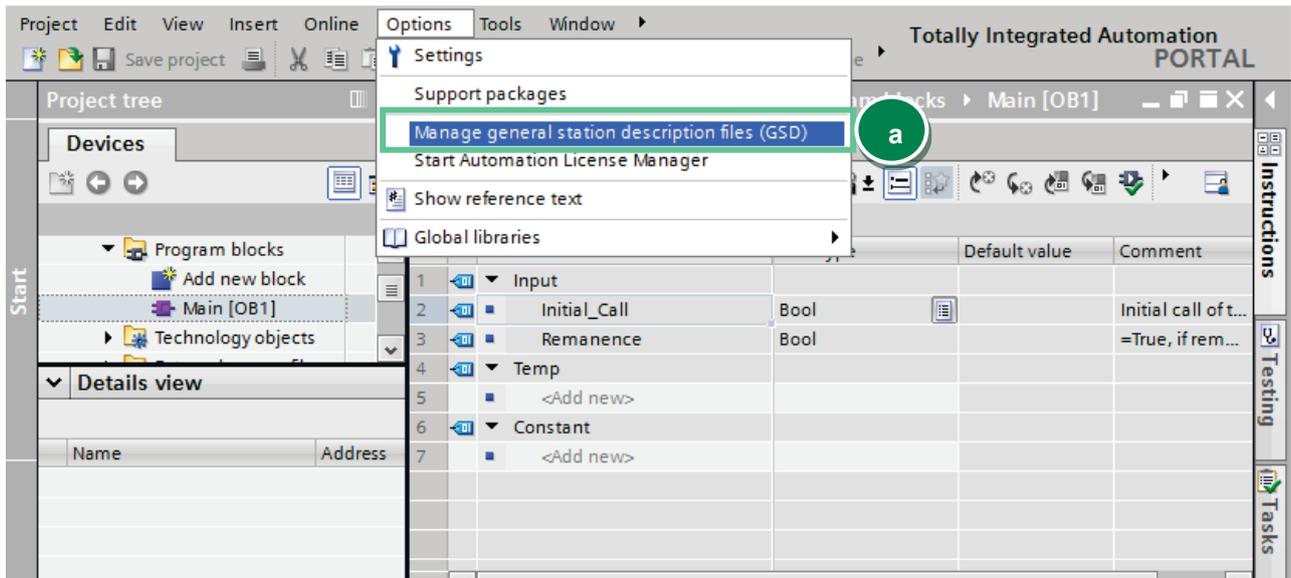
- Go to **Devices & networks** (a) on the left side select **Add new device** (b) and look for your CPU (c). Afterwards click the **Add** button (d).



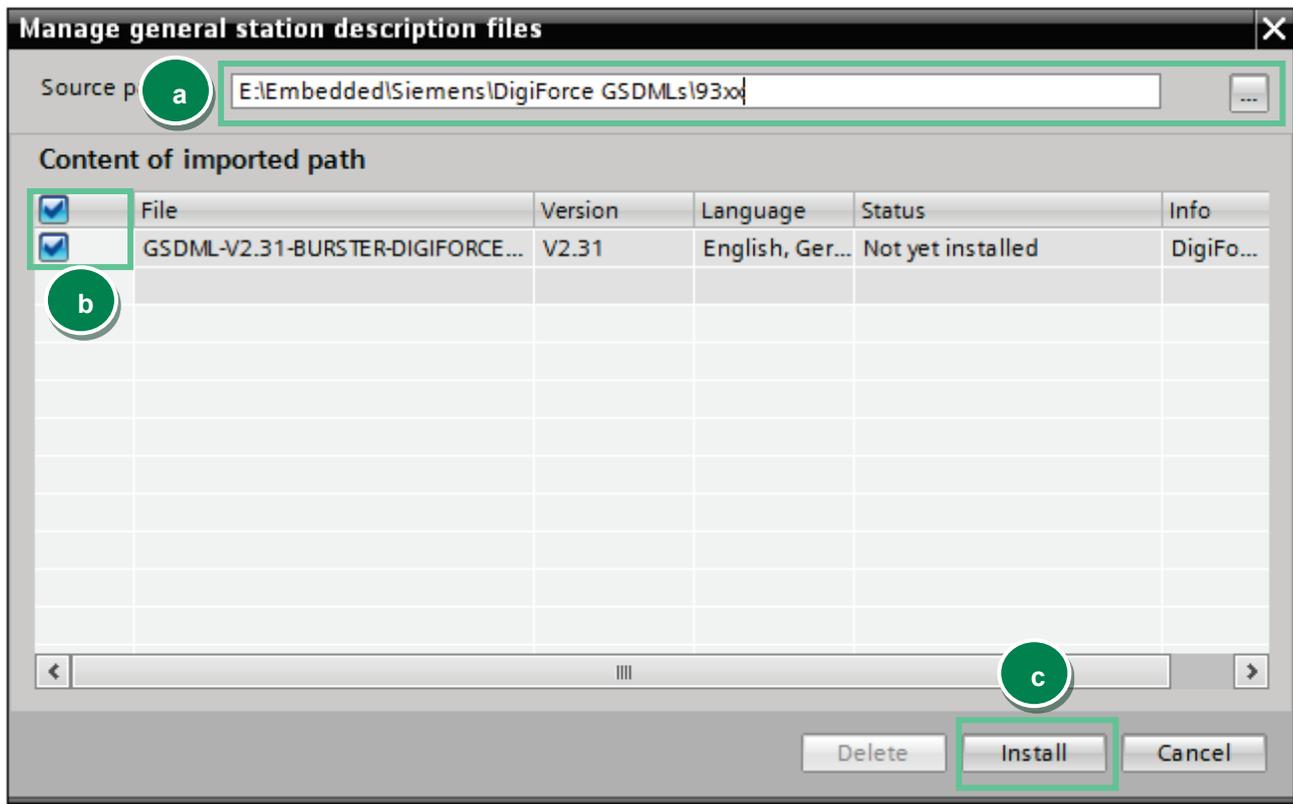
2. Installation of GSDML files

Note: Please make sure that your GSDML file is compatible to the field bus firmware in the DIGIFORCE® 9307. Also for compatibility reasons, uninstall all previous GSDML files of particular device if you have any!

- Go to **Options->Manage general station description files (GSD)**

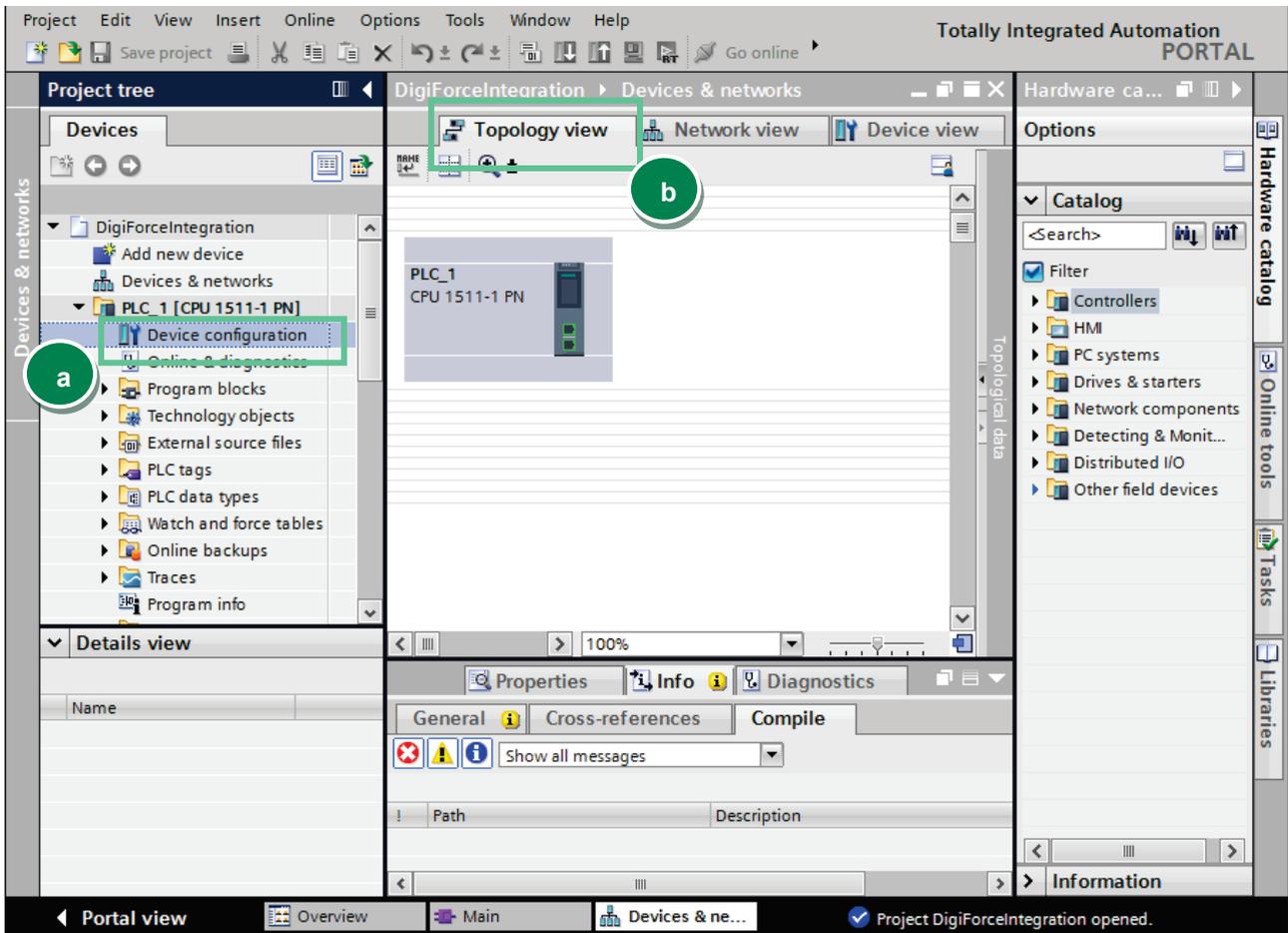


- Navigate to your DIGIFORCE® 9307 GSDML directory (a)(you will find the GSDML files on burster DVD that you got with your DIGIFORCE® 9307 device or on www.burster.com), select the GSDML file (b) and click **Install** (c)

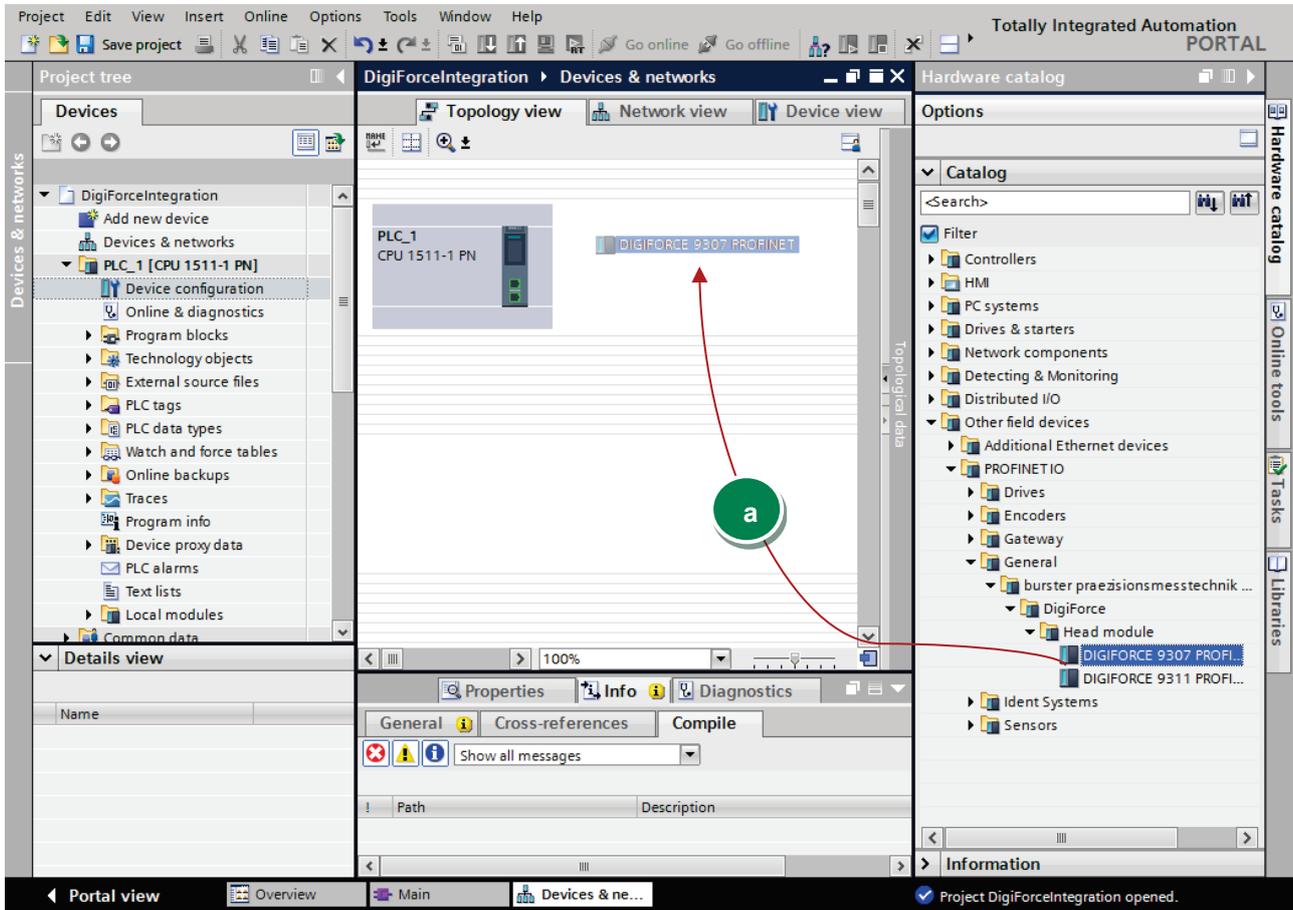


3. Creation of network connections

- Double click **Device Configuration** (a) in the project tree und switch to **Topology view** (b):

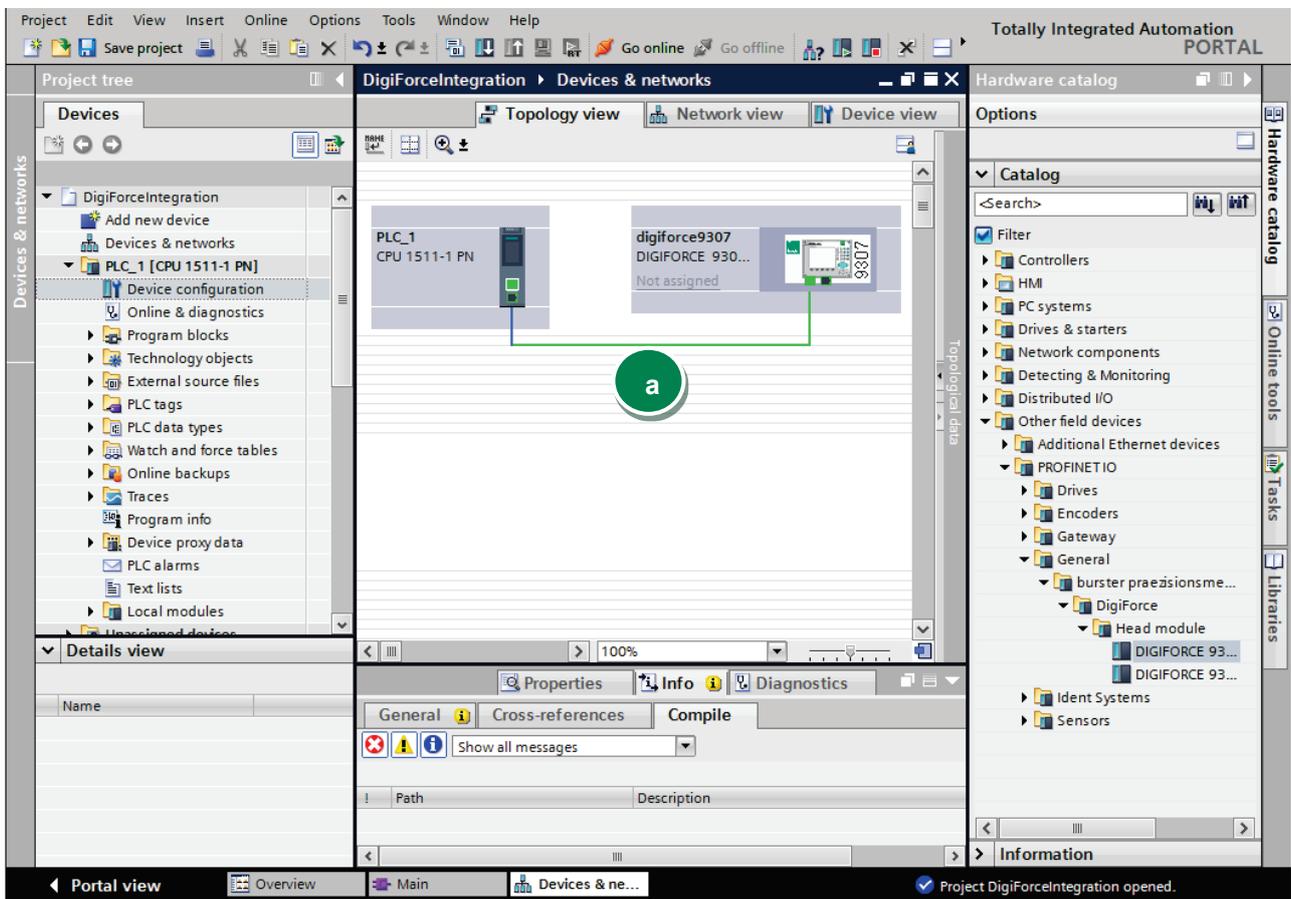


- Now select the DIGIFORCE[®] 9307 device in the catalog and drag & drop it into the working area (a):



DIGIFORCE® 9307 PROFINET

- Please select an ethernet port on the S7 and hold the left mouse button down to connect the S7 with DIGIFORCE® 9307:



- Change now to **Network view** (a) to assign a controller to the DIGIFORCE® 9307. Click on the link “Not assigned” (b) of DIGIFORCE® 9307 and select your controller (c):

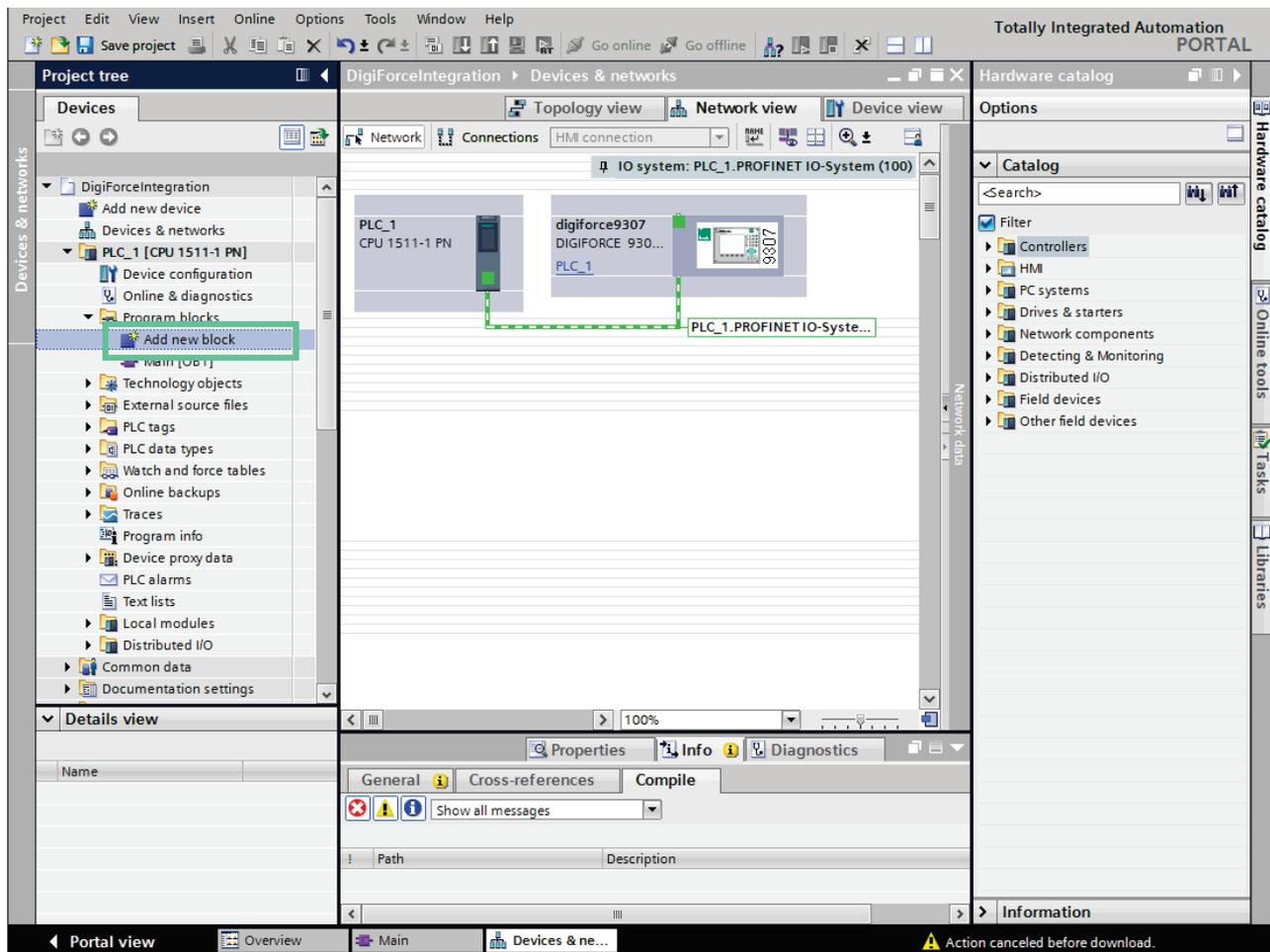
The screenshot displays the 'Totally Integrated Automation PORTAL' software interface. The main window is titled 'DigiForceIntegration > Devices & networks' and is in 'Network view' (a). The network diagram shows a 'PLC_1 CPU 1511-1 PN' connected to a 'digiforce9307 DIGIFORCE 9307' device. The device is currently 'Not assigned' (b) and has a link 'Select IO controller PLC_1.PROFINET interface'. A green circle (c) highlights the 'PN/E_1' port on the device. The left sidebar shows the 'Project tree' with 'DigiForceIntegration' expanded to 'PLC_1 [CPU 1511-1 PN]'. The right sidebar shows the 'Hardware catalog' with a search bar and a filter set to 'Controllers'. The bottom status bar indicates 'Project DigiForceIntegration opened.'

- Check if devices also connected physically to the right ports. You find the port number assignment in the section 5.3 *Port-Identification* of **DIGIFORCE® 9307 PROFINET** manual.

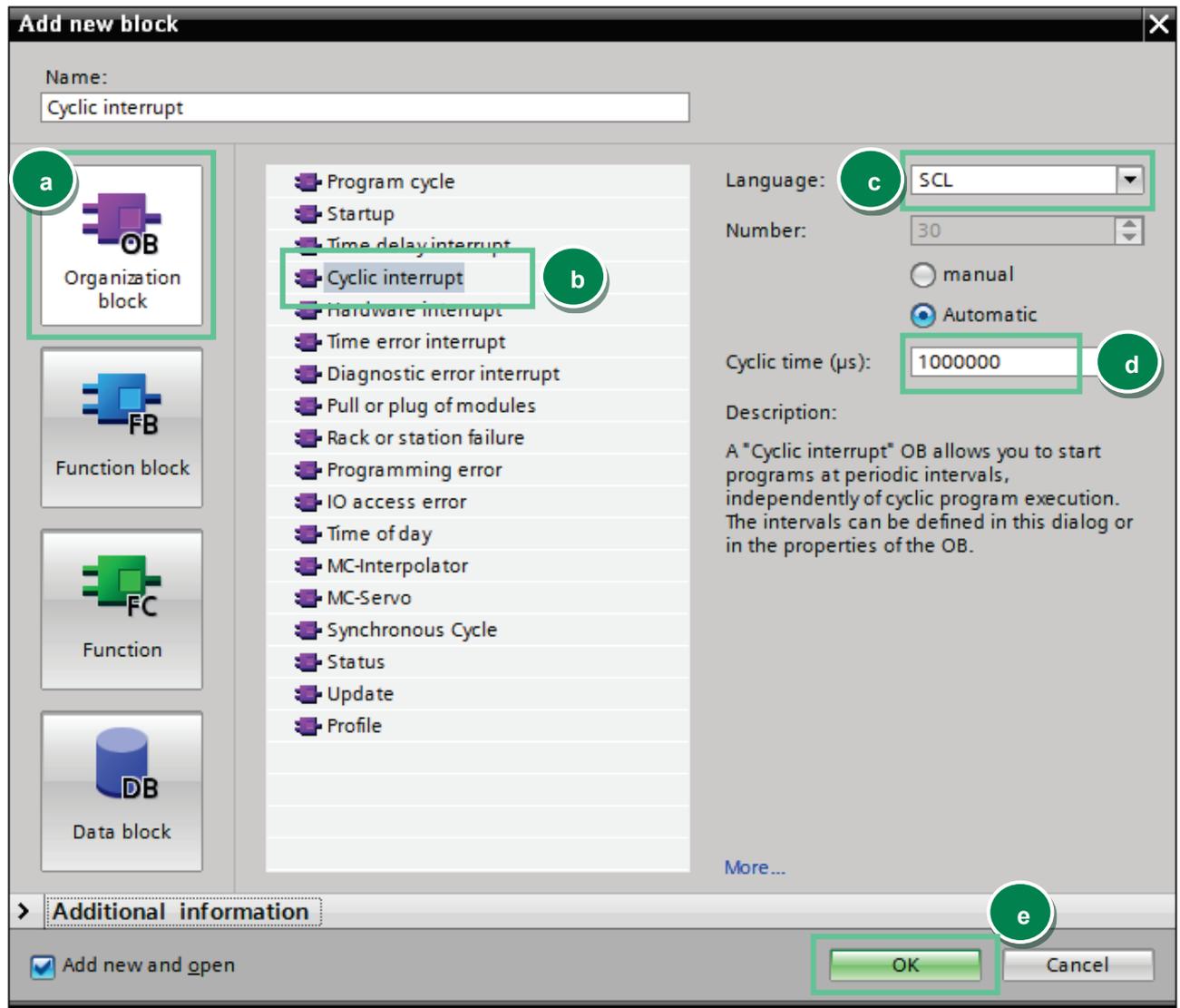
4. Create a sample program:

In this section, you will learn how to create a simple program to start and stop a measurement periodically. You will need to refer to sections 8.2 PLC inputs and 8.3 PLC outputs of **DIGIFORCE® 9307 PROFINET** manual to understand the meaning of inputs and outputs bytes.

- Expand the tree node **Program blocks** in the Project tree and double click **Add new block**:



- Select in the new window **Organization block** (a) and then **Cyclic interrupt** (b). As language set SCL (c), change the cyclic time to 1.000.000 µs (d) and click OK (e):



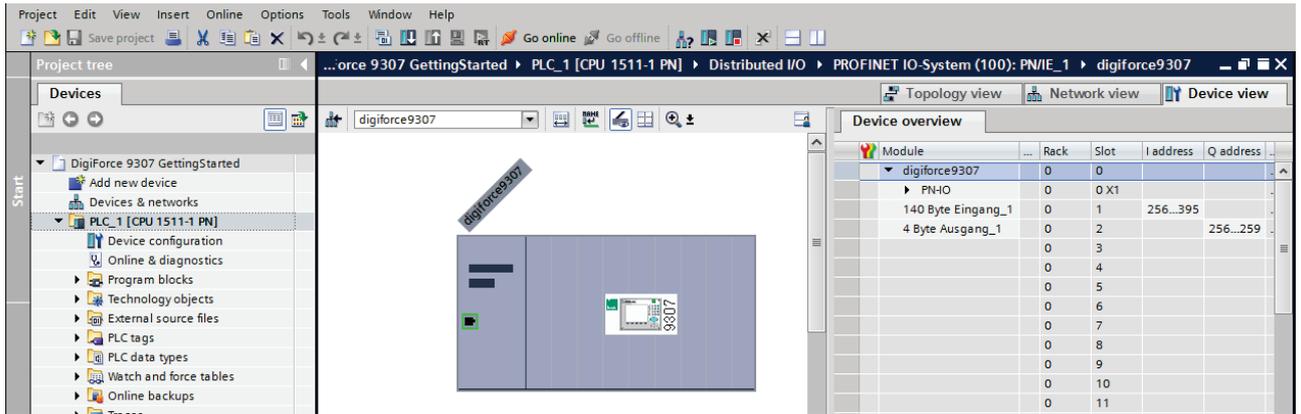
- Type in the following source code in the code field of the new block:

```

IF %Q259.0 = TRUE THEN      // is IN_START (measurement start) set?
  %Q259.0 := FALSE;        // IN_START (measurement start) is set, then reset it
ELSE                          // IN_START is not set
  IF %I256.0 = FALSE THEN   // is OUT_READY (DigiForce ready for measurement) set?
    RETURN;                 // If not -
                            // return
  END_IF;
  %Q259.0 := TRUE;         // set IN_START(measurement start)
END_IF;

```

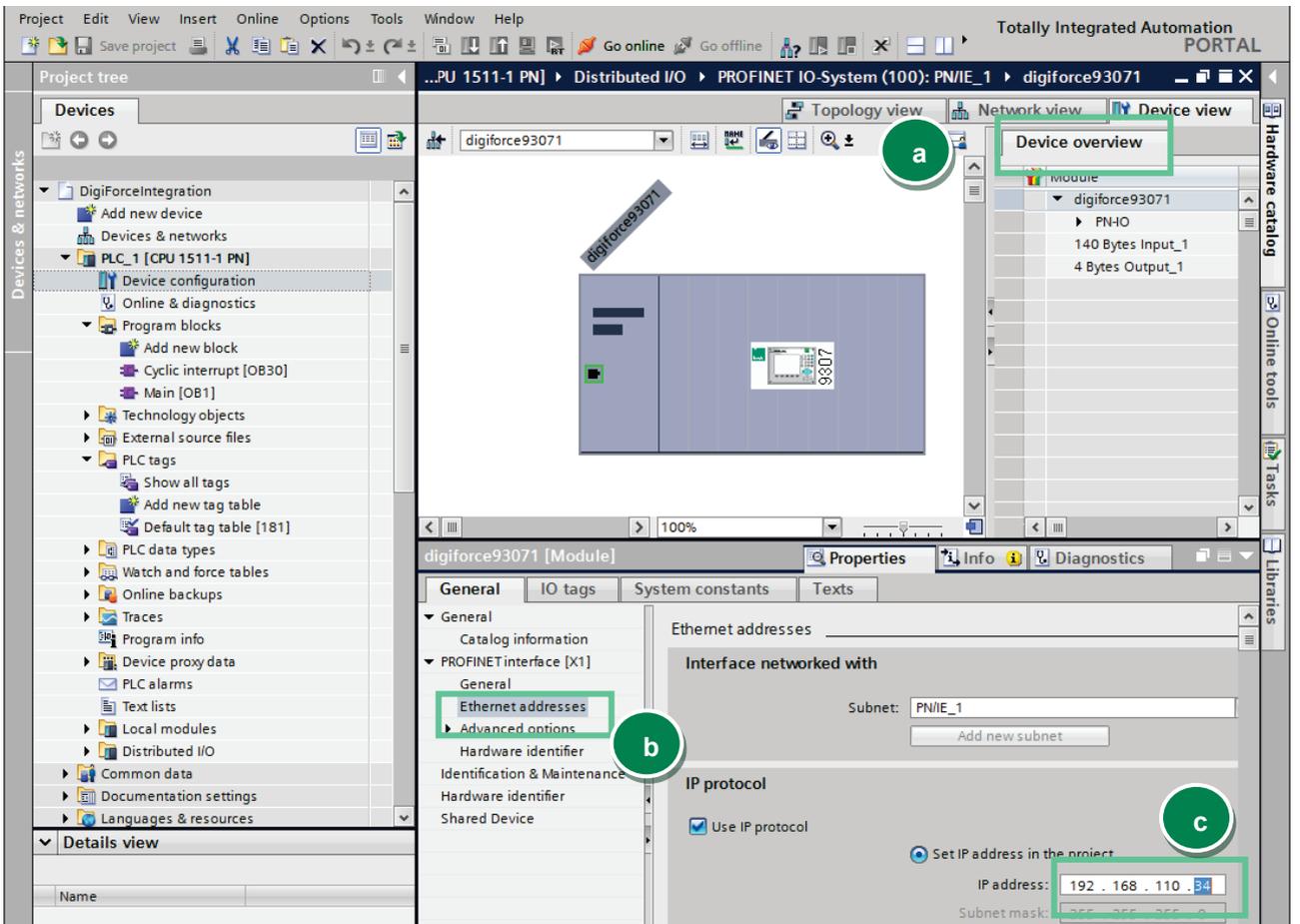
Please note: the addresses may be different. You have to check them in the **Device view->Device overview** of the DIGIFORCE® 9307.



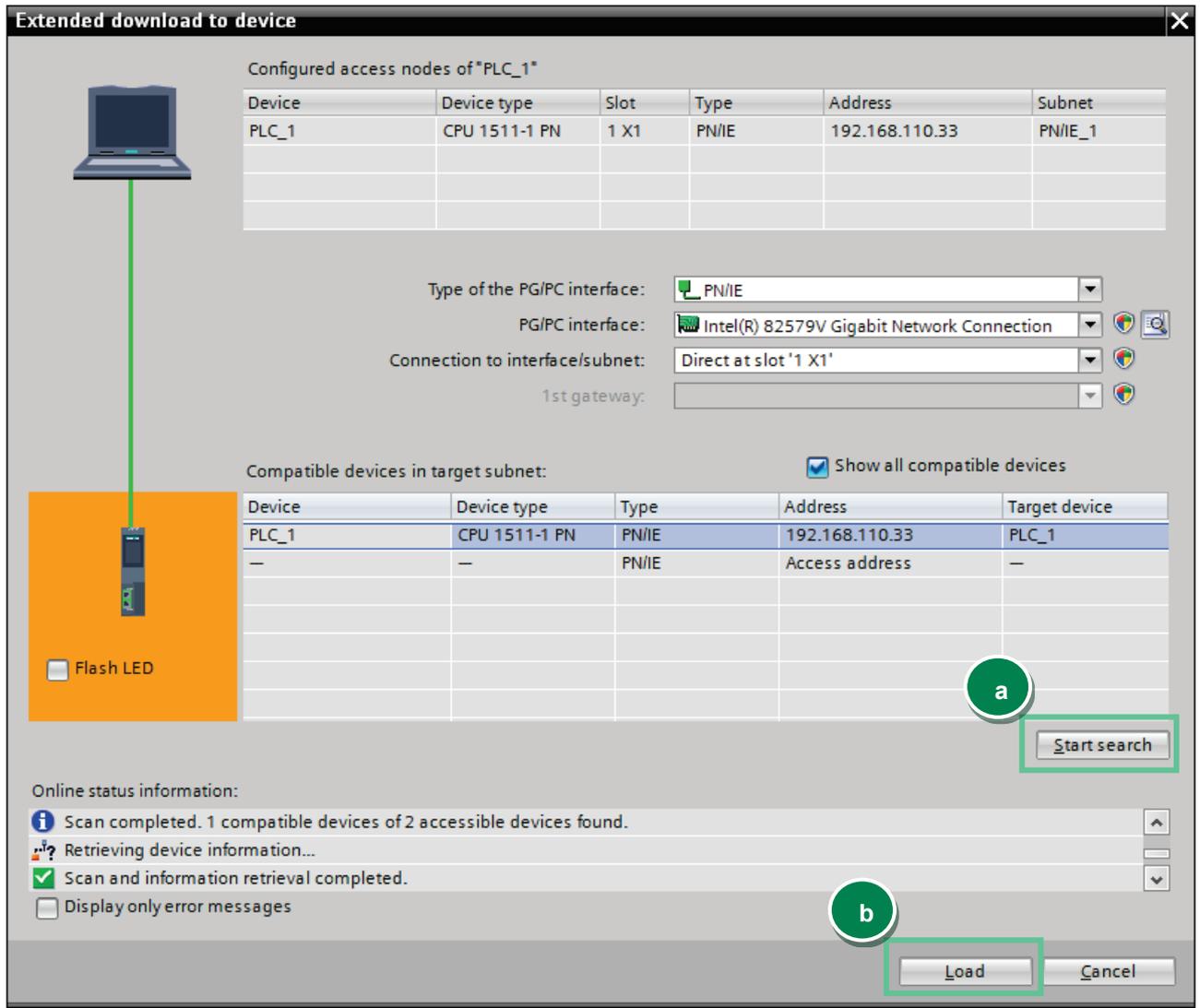
You will also see that the TIA-Editor replaces the input/output addresses with tags. You can change the tags names in PLC Tag table:

PLC tags							
	Name	Tag table	Data type	Address	Retain	Visibl...	Acces...
1	OUT_READY	Standard-Variablen...	Bool	%I256.0	<input type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>
2	IN_START	Standard-Variablen...	Bool	%Q259.0	<input type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>

- Before you load the project into the CPU you have to set the IP addresses of your controller and your device. To do this please go to **Device view** (a) and select **Ethernet addresses** (b) in **General** tab. Set now a desired IP-Address (c):



- To load the configuration into the CPU select it first and then go to **Online->Download to device** and click on **Start search** (a) to look for your controller. Then select the controller and click on **Load** (b):

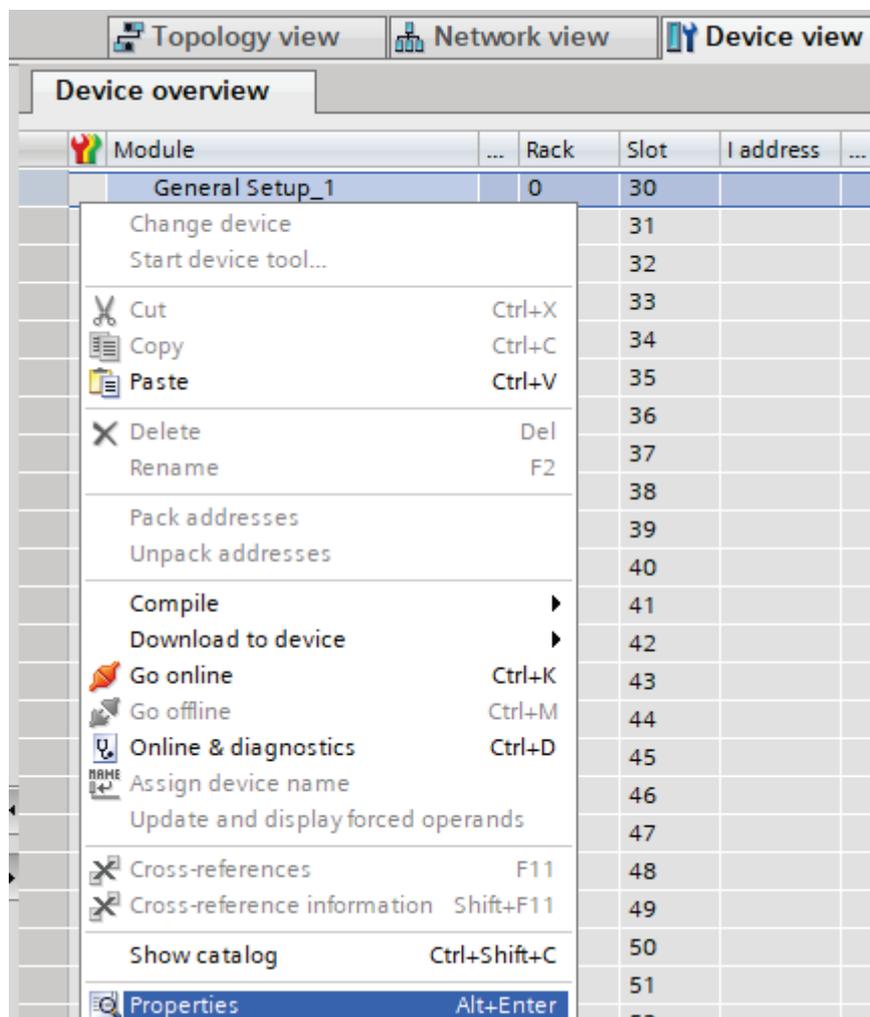


The DIGIFORCE® 9307 starts now a new measurement waits a second, and stops the measurement, waits a second and starts the measurement again and so on.

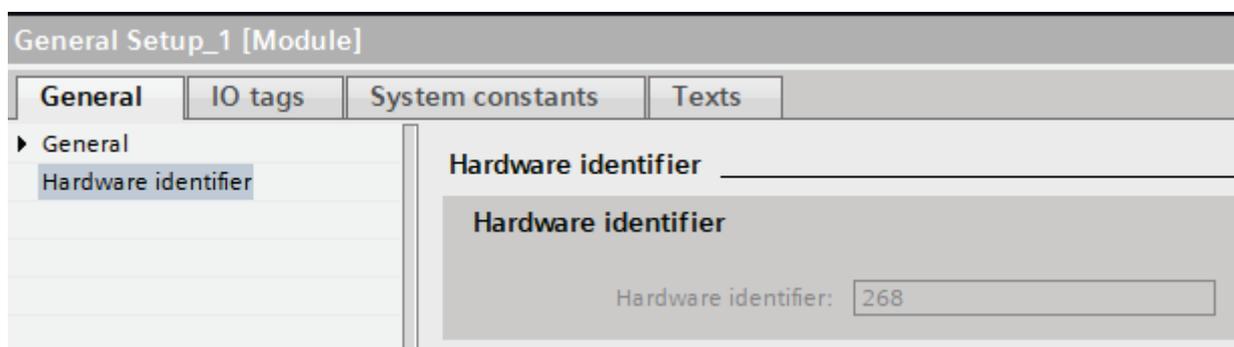
Note: Make sure that PROFINET Control is enabled in DIGIFORCE® 9307. For details, see chapter 5.5 Configuration menu in DIGIFORCE® 9307 of DIGIFORCE® 9307 PROFINET manual.

5. Further Examples

In the followed examples, a *Hardware-ID* is used to access a certain slot. To find this, please select a DIGIFORCE® 9307 device in **Topology view** or **Network view** and then switch to **Device view**. Click with the right mouse button on the desired module, e.g. *General Setup* and select **Properties**:



You will see the hardware identifier in the tab **General**:



5.1 Reading and Writing of string data types

In this example, we perform a read access on slot 30/Subslot 1/index 10 to get the device type of DIGIFORCE® 9307 and then we will set the first nine characters of this string as DIGIFORCE® 9307 station name on Slot 30/Subslot 1/Index 19. For these acyclic operations, you will need an instance of RDREC und WRREC blocks. You can see the new station name in the **info menu** of DIGIFORCE® 9307.

PLC parameters table:

5		Valid	Standard-Variablen...	Bool
6		Busy	Standard-Variablen...	Bool
7		Error	Standard-Variablen...	Bool
8		Status	Standard-Variablen...	DWord
9		Done	Standard-Variablen...	Bool
10		lenRead	Standard-Variablen...	UInt

Sourcecode:

```

REPEAT
"RDREC_DB"(REQ:=TRUE,
  ID := 268,           // 268: HW-ID for General Setup (see introduction of 'Further examples')
  INDEX:=10,          // Index 10: Device Detection
  MLEN:=18,           // Max. length of data to read
  VALID=>#Valid,      // New Data Received and valid
  BUSY=>#Busy,        // Read not completed yet
  ERROR=>#Error,      // Error
  STATUS=>#Status,    // State
  LEN=>#lenRead,      // Number of bytes was read from device
  RECORD:= #data);   // Array[0..18] of Byte
UNTIL NOT #Busy
END_REPEAT;

IF #Error = TRUE OR #Status <> 0 THEN
  RETURN;
END_IF;

REPEAT
"WRREC_DB"(REQ:=TRUE,
  ID := 268,           // HW-ID for General Setup (see introduction of 'Further examples')
  INDEX:=19,          // Index 19: Station Name
  LEN:=9,             // Length of data to write
  DONE=>#Done,        // Write done
  BUSY=>#Busy,        // Write not completed yet
  ERROR=>#Error,      // Error
  STATUS=>#Status,    // State
  RECORD:=#data);    // Write the data has being read in RDREC_DB (first 9 bytes)
UNTIL NOT #Busy AND #Done
END_REPEAT;

```

Example 2: Writing of serial number SN1 into device order sheet

Note: Datatype **String** in TIA Portal contains two additional bytes, which represent the length of the string. To avoid these two bytes being sent use the function 'Strg_TO_Chars' to convert the String to a byte array as shown below:

PLC parameters table:

Name	Data type	Default value
serial	String	
bytesWritten	UInt	
serialAsByteArray	Array[0..64] of Byte	
Busy	Bool	
Error	Bool	
Status	DWord	
Done	Bool	

Sourcecode:

```
#serial := 'SN123456789';

Strg_TO_Chars(Strg:= #serial,           // Serial as String
              pChars:= 0,              // Position in serialAsByteArray
              Cnt => #bytesWritten,     // Number of Bytes have been written to serialAsByteArray
              Chars:= #serialAsByteArray);

REPEAT
  "WRREC_DB"(REQ := TRUE,
             ID := 268,                // HW-ID General Setup (see introduction of 'Further examples')
             INDEX := 86,              // Index 86: Order sheet - Serial number 1
             LEN := INT_TO_UINT(LEN(#serial)), // Length of serial
             DONE => #Done,            // Write done
             BUSY => #Busy,            // Write not completed yet
             ERROR => #Error,         // Error
             STATUS => #Status,       // State
             RECORD := #serialAsByteArray);
UNTIL NOT #Busy AND #Done
END_REPEAT;
```

5.2 Retrieving of measurement results

Note: The reading of all X- or Y-Coordinates of a curve an once is only supported in the DIGIFORCE[®] 9307 PROFINET Firmware V16.0.1 and higher.

This example shows you how to read the X-Coordinates of the current curve:

PLC parameters tables:

4	Temp		
5	Valid	Bool	
6	Done	Bool	
7	Busy	Bool	
8	Error	Bool	
9	Status	DWord	
10	i	Int	
11	lastIndex	DWord	
12	lenRead	UInt	
13	measVal	DWord	
14	tmp	DWord	

PLC program	Add new device		
	Devices & networks		
	PLC_1 [CPU 1511-1 PN]	✓	
	Device configuration		
	Online & diagnostics		
	Program blocks	●	
	Add new block		
	Cyclic interrupt [OB30]	●	
	Diagnostic error interrupt [OB82]	●	
	Main [OB1]	●	
	Startup [OB100]	●	
	Tare&Measurement [FB1]	●	
	Data [DB4]	●	

1	Static	
2	data	Array[0..20000] of Byte
3	coordinates	Array[0..5000] of Real
4	coordinates[0]	Real
5	coordinates[1]	Real
6	coordinates[2]	Real
7	coordinates[3]	Real
8	coordinates[4]	Real
9	coordinates[5]	Real
10	coordinates[6]	Real
11	coordinates[7]	Real
12	coordinates[8]	Real
13	coordinates[9]	Real

Sourcecode:

```

REPEAT
  "WRREC_DB"(REQ := TRUE,
    ID := 454, // Write access to index 10 to prepare the curve
    INDEX := 10, // HW-ID (see introduction of 'Further examples')
    LEN := 2, // Index
    DONE => #Done, // Length in bytes to write
    BUSY => #Busy,
    ERROR => #Error,
    STATUS => #Status,
    RECORD := "Data".data); // Any 2 bytes to prepare the curve
UNTIL NOT #Busy AND #Done
END_REPEAT;

IF #Error = TRUE OR #Status <> 0 THEN
  RETURN; // If write failed -> return
END_IF;

REPEAT

```

```

"RDREC_DB"(REQ := TRUE,
  ID := 454,
  INDEX := 10,
  MLEN := 4,
  VALID => #Valid,
  BUSY => #Busy,
  ERROR => #Error,
  STATUS => #Status,
  LEN => #lenRead,
  RECORD := #lastIndex);
UNTIL NOT #Busy
END_REPEAT;

#lastIndex := SHR(IN := #lastIndex, N := 16);

IF #Error = TRUE OR #Status <> 0 OR #lenRead <> 2 OR
#lastIndex = 0 THEN
  RETURN;
END_IF;
REPEAT
  "RDREC_DB"(REQ := TRUE,
    ID := 454,
    INDEX := 11,
    MLEN := 20000,
    VALID => #Valid,
    BUSY => #Busy,
    ERROR => #Error,
    STATUS => #Status,
    LEN => #lenRead,
    RECORD := "Data".data);
UNTIL NOT #Busy
END_REPEAT;

IF #Error = TRUE OR #Status <> 0 OR #lenRead < 4
THEN
  RETURN;
END_IF;

FOR #i := 0 TO DWORD_TO_INT(#lenRead - 1) BY 4 DO
  #measVal := 0;
  #tmp := BYTE_TO_DWORD("Data".data[#i]);
  #measVal := #measVal + SHL(IN := #tmp, N := 24);
  #tmp := BYTE_TO_DWORD("Data".data[#i + 1]);
  #measVal := #measVal + SHL(IN := #tmp, N := 16);
  #tmp := "Data".data[#i + 2];
  #measVal := #measVal + SHL(IN := #tmp, N := 8);
  #measVal := #measVal + "Data".data[#i + 3];
  "Data".coordinates[#i / 4] :=
DWORD_TO_REAL(#measVal);
END_FOR;

```

// Read the number of curve values
// HW-ID (see introduction of 'Further examples')
// Index
// Max. length to read

// Number of bytes read
// Number of values in the curve - 1

// upto and including DIGIFORCE® 9307 field bus
firmware FW-2018.1.0 we have to use DWord to get
U16 Types from DIGIFORCE® 9307 und shift left
the result by 2 bytes

// If read failed -> return

// Read access to read out curve coordinates
// HW-ID(see introduction of 'Further examples')
// Index
// Max. length to read

// Number of bytes read
// Array to store the read coordinates

// If read failed -> return

// Write bytes to DWORD and convert to Real
// Shift left the value by 24 bit
// Shift left the value by 16 bit
// Shift left the value by 8 bit
// Convert to Real and store in MeasValues[] Array

5.3 Changing of window limits

This example shows you how to enable Evaluation Window 1 and set its coordinates.

Note: You have to write all four window limits and then confirm them with index 15. It is not possible to change only one single limit, e.g. xMax.

PLC parameters table:

Name	Data type	Default value
Temp		
Busy	Bool	
Error	Bool	
Status	DWord	
onOff	UInt	
xMin	Real	
xMax	Real	
yMin	Real	
yMax	Real	
event	Byte	
Done	Bool	
Constant		

Sourcecode:

```
#onOff := 1;           // Activate Window 1
#event := 1;          // Acknowledgement for indices 11, 12, 13,14

#xMin := 1.5;         // Xmin coordinate of window 1
#xMax := 3.0;         // Xmax coordinate of window 1
#yMin := 2.5;         // Ymin coordinate of window 1
#yMax := 4.0;         // Ymax coordinate of window 1

REPEAT
  "WRREC_DB"(REQ := TRUE,
    ID := 298,          // HW-ID for Evaluation Window 1 (see introduction of 'Further examples')
    INDEX := 10,       // Index 10: switch on window 1
    LEN := 2,          // Length of UINT16
    DONE => #Done,     // Write done
    BUSY => #Busy,     // Write not completed yet
    ERROR => #Error,   // Error
    STATUS => #Status, // State
    RECORD := #onOff);
UNTIL NOT #Busy AND #Done
END_REPEAT;

REPEAT
  "WRREC_DB"(REQ := TRUE,
    ID := 298,          // HW-ID for Evaluation Window 1 (see introduction of 'Further examples')
    INDEX := 11,       // Index 11: Window 1 limit Xmin
    LEN := 4,          // Length of UINT16
    DONE => #Done,     // Write done
    BUSY => #Busy,     // Write not completed yet
    ERROR => #Error,   // Error
    STATUS => #Status, // State
```

```

RECORD := #xMin);
UNTIL NOT #Busy AND #Done
END_REPEAT;

REPEAT
  "WRREC_DB"(REQ := TRUE,
    ID := 298,           // HW-ID for Evaluation Window 1 (see introduction of 'Further examples')
    INDEX := 12,        // Index 12: Window 1 limit Xmax
    LEN := 4,           // Length of Real
    DONE => #Done,      // Write done
    BUSY => #Busy,       // Write not completed yet
    ERROR => #Error,    // Error
    STATUS => #Status,  // State
    RECORD := #xMax);
UNTIL NOT #Busy AND #Done
END_REPEAT;

REPEAT
  "WRREC_DB"(REQ := TRUE,
    ID := 298,           // HW-ID for Evaluation Window 1 (see introduction of 'Further examples')
    INDEX := 13,        // Index 13: Window 1 limit Ymin
    LEN := 4,           // Length of Real
    DONE => #Done,      // Write done
    BUSY => #Busy,       // Write not completed yet
    ERROR => #Error,    // Error
    STATUS => #Status,  // State
    RECORD := #yMin);
UNTIL NOT #Busy AND #Done
END_REPEAT;

REPEAT
  "WRREC_DB"(REQ := TRUE,
    ID := 298,           // HW-ID for Evaluation Window 1 (see introduction of 'Further examples')
    INDEX := 14,        // Index 14: Window 1 limit Ymax
    LEN := 4,           // Length of Real
    DONE => #Done,      // Write done
    BUSY => #Busy,       // Write not completed yet
    ERROR => #Error,    // Error
    STATUS => #Status,  // State
    RECORD := #yMax);
UNTIL NOT #Busy AND #Done
END_REPEAT;

REPEAT
  "WRREC_DB"(REQ := TRUE,
    ID := 298,           // HW-ID for Evaluation Window 1 (see introduction of 'Further examples')
    INDEX := 15,        // Index 15: adopt values entered into indices 11, 12, 13,14
    LEN := 1,           // Length of Real
    DONE => #Done,      // Write done
    BUSY => #Busy,       // Write not completed yet
    ERROR => #Error,    // Error
    STATUS => #Status,  // State
    RECORD := #event);
UNTIL NOT #Busy AND #Done
END_REPEAT;

```